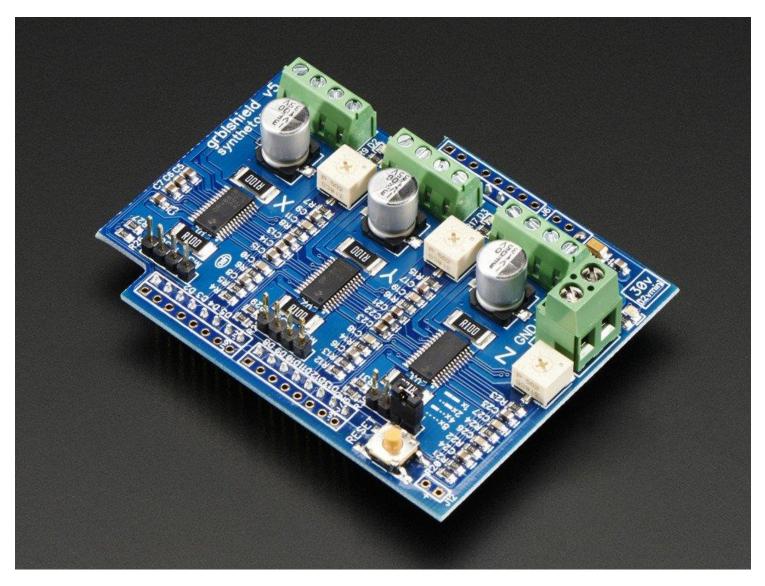
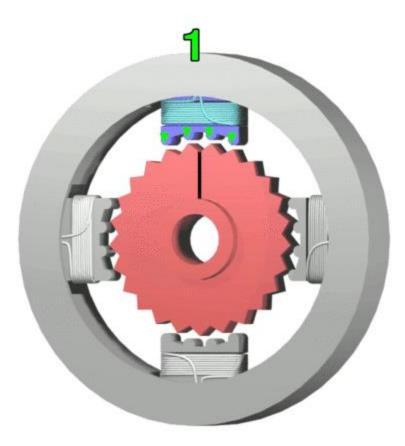
Inventables CNC Machine

M. Neilsen

Synthetos gShield + Arduino with grbl

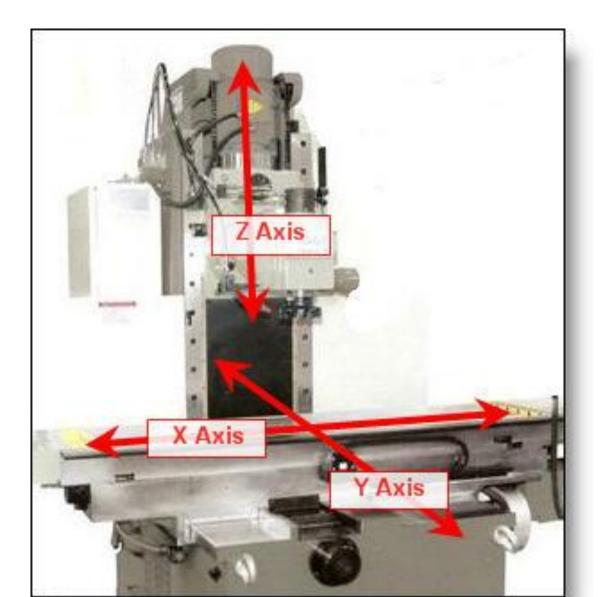


Stepper Motors



<u>Four Phase Unipolar Stepper:</u> <u>https://learn.adafruit.com/all-about-stepper-motors</u>

3-Axis CNC Machine



Terminology

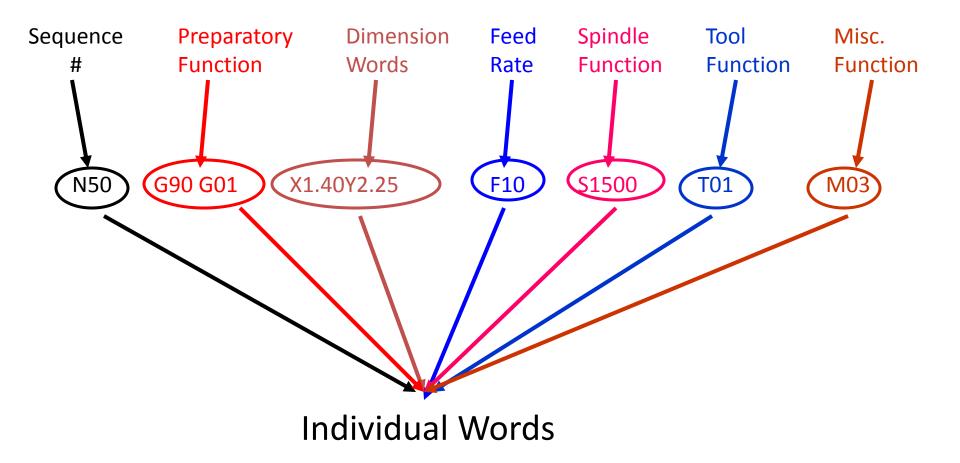
- NC Numerical Control
- CNC Computer Numerical Control
- CAD Computer Aided Design
- CAM Computer Aided Manufacturing

G - Code Programming

- G Code Programming
- Originally called the "word address" programming format

• Processed **sequentially**, **one line** at a time

Common Format of a Block



G Word

- **G words or codes** tell the machine to perform certain functions.
- Most G words are modal which means they remain in effect until replaced by another modal G code.

Common G Codes

- G00 Rapid positioning mode move along the shortest route to the programmed X,Y,Z position. Usually NOT used for cutting.
- G01 Linear interpolation mode move along a straight-line path at programmed rate of speed.
- G02 Circular motion clockwise (cw)
- G03 Circular motion counter clockwise (ccw)

Common G Codes ..

- G17 XY plane
- G18 XZ plane
- G19 YZ plane
- G20 Inch Mode
- G21 Metric Mode
- G28 Return to axis machine zero (go home)

Universal G-Code Sender

https://github.com/winder/Universal-G-Code-Sender

Universal Gcode Sender (Version 1.0.8 [nigh	tly] 2015-01-09 00:02:21 EST)
Settings Pendant	
Connection Port: COM30 Baud: 115200 GRBL Open Firmware: GRBL	Commands File Mode Machine Control Macros Command:
Machine status Active State: Latest Comment: Work Position: Machine Position: X: 0 X: 0 Y: 0 Y: 0	
Z: 0 Z: 0	🗹 Scroll output window 🗌 Show verbose output
Console Command Table	

) 🔿 🤿	Universal GcodeSender (Version 1.0.6)					
Connection	Commands File Me	ode Ma	chine Co	ntrol		
Port: /dev/tty.usbmodem621	File C/projects/OrdBot/b17049_rev_2-bot foot - 8.2 thick - 1.6 tool.nc					Browse
	Send Paus		Cancel]	(Visualize
Machine status	Override speed %			Row	s In File: 766	
Active State: Run Latest Comment: Outside	Estimated Time Remain	ning: 00:0 tion: 00:0			nt Rows: 646	
Work Position: Machine Position:	Dula	uon. 00.	07.45	Kemainin	g Rows: 117	
X: 7.771 X: 7.771 Y: 7.246 Y: 7.246						
7: -6.631 7: -6.631	✓ Scroll output window [Show v	erbose o	output		
Console Command Table						
Command		Sent	Done	Response		
G0 Z-6.2 G1 X0.5089 Y43.1691		\checkmark	\checkmark	ok ok		
G1 F300.0 Z-7.0		V		ok		
G1 F1000.0 X6.9429 Y9.9696		✓ ✓	Ĭ	ok		
G3 X7.7827 Y7.2438 I13.0571 J2.5304	ļ.	\checkmark	< </td <td>ok</td> <td></td> <td></td>	ok		
G0 Z-6.2		< </td <td>\checkmark</td> <td>ok</td> <td></td> <td></td>	\checkmark	ok		
G3 X9.6399 Y4.1598 I12.2173 J5.2562	2	\checkmark				
G1 F300.0 Z-7.0		\checkmark				
G3 F1000.0 X33.0571 Y9.9696 I10.36	01 18.3402	\checkmark				

Easel (<u>http://easel.inventables.com</u>)

